

# TRC Canonical Modulation Architecture

## Neutral Rewrite with Implementable Metrics

### 1. Overview

This system defines a dual-layer modulation architecture for dynamically adjusting a scalar trust signal. It combines numerical signal processing with a configurable biasing mechanism. The goal is to maintain stable, interpretable system outputs by regulating curvature and filtering interference.

### 2. Core Signal Definitions

- $T$  — Trust scalar, real number in  $[-1, 1]$
- $\frac{dT}{dt}$  — First derivative (rate of change)
- $\frac{d^2T}{dt^2}$  — Second derivative (curvature)
- $I_c$  — Internal consistency (bounded in  $[0, 1]$ )
- $\Xi$  — Symbolic interference (noise coefficient in  $[0, 1]$ )
- $\kappa_{\max}$  — Curvature clamp threshold
- $A_{\text{mod}}$  — Output modulation adjustment
- $B_n$  — Bias tier  $n \in \{1, \dots, 8\}$  for weighting control parameters

### 3. Modulation Bias Function

Bias is computed as:

$$A_{\text{mod}} = \max \left( 0.05, B_n \times 0.01 \times \left| \frac{d^2T}{dt^2} \right| \cdot (1 - \Xi) \cdot I_c \right)$$

Each  $B_n$  corresponds to a bias function described below. All terms are numerical and bounded. This function outputs a capped trust modulation value adjusted for stability and interference.

## 4. Modulation Pipeline

1. Accept raw trust signal  $T$ .
2. Derive momentum and curvature.
3. Apply symbolic interference coefficient  $\Xi$ .
4. Clamp curvature if  $|\frac{d^2T}{dt^2}| > \kappa_{\max}$ .
5. Compute  $A_{\text{mod}}$  via bias function.
6. Output updated trust  $T' = T + A_{\text{mod}}$ .

## 5. System Parameters and Bias Tiers

Each tier corresponds to an independent control vector.

1. **Data Consistency** — assesses input agreement across sources.
2. **Evidence Responsiveness** — tunes weight assigned to new inputs vs. historical inertia.
3. **Change Stability** — controls acceleration tolerance to avoid erratic behavior.
4. **Conflict Resolution** — reduces modulation when contradictory data is detected.
5. **Delay Tolerance** — increases buffer window for late-arriving or asynchronous data.
6. **Error Minimization** — penalizes modulation under high uncertainty or self-contradiction.
7. **Fairness Bias** — allocates modulation evenly across competing inputs.
8. **Meta-Adjustment** — dynamic tier that adapts other bias values using system-wide heuristics.

Each tier outputs a weighting coefficient  $B_n \in [0.5, 1.5]$  depending on policy or configuration.

## 6. Implementation Functions

### 6.1 Quantizer

```
float compute_modulation(curvature, Xi, Ic, Bn):
```

1. Compute:  $A = \max(0.05, B_n \cdot 0.01 \cdot |\text{curvature}| \cdot (1 - \Xi) \cdot Ic)$
2. Return  $A$

## 6.2 Regulator

`float modulate_trust(T, Xi, Ic, Bn, curvature):`

1. Clamp:  $curvature = \min(curvature, \kappa_{max})$
2.  $A = compute\_modulation(curvature, Xi, Ic, Bn)$
3. Return  $T' = T + A$

## 7. Test Protocol

- Simulate trust  $T = 0$  for  $t = 0 \dots 50$
- Inject  $\Xi = 0.8$  at  $t = 20$
- Set  $I_c = 0.95$ ,  $Bn = 1.2$ ,  $\kappa_{max} = 0.6$
- Log:  $T$ ,  $A_{mod}$ ,  $\Xi$ ,  $curvature$
- Validate  $T'$  trajectory remains stable and bounded

## 8. Output Format

Data is exported per timestep:

- [timestamp, T, curvature, A\_mod, Xi, Ic, Bn]
- Output to CSV or real-time log for analysis

## 9. Containment Guarantees

- Symbolic recursion is reduced by bounding modulation under interference.
- Emotional or philosophical labels are excluded from control flow.
- Tier weights are tunable but interpreted numerically only.
- System does not model or reflect identity or beliefs—only signal coherence and responsiveness.